

IsoChronoMeter: A simple and effective isochronic translation evaluation metric

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Abstract

Machine translation (MT) has come a long way and is readily employed in production systems to serve millions of users daily. With the recent advances in generative AI, a new form of translation is becoming possible - video dubbing. This work motivates the importance of isochronic translation, especially in the context of automatic dubbing, and introduces ‘IsoChronoMeter’ (ICM). ICM is a simple yet effective metric to measure isochrony of translations in a scalable and resource-efficient way without the need for gold data, based on state-of-the-art text-to-speech (TTS) duration predictors. We motivate IsoChronoMeter and demonstrate its effectiveness. Using ICM we demonstrate the shortcomings of state-of-the-art translation systems and show the need for new methods. We release the code at this URL: <https://github.com/braskai/isochronometer>.

1 Introduction

The isochronic translation is a practice of ensuring that the timing of speech in translated content matches the original. It has become increasingly crucial in AI-driven dubbing. As the demand for multilingual audiovisual content grows, the ability to maintain the natural rhythm and pacing of the original language through isochronic translation is vital for the success of AI dubbing systems. Traditionally, human translators and voice actors have emphasized the importance of synchronizing translated dialogue with on-screen visuals to ensure a seamless viewing experience. This synchronization, known as isochrony, is essential for maintaining the illusion that the actors are speaking the translated language, matching their lip movements and pauses with the new audio. Recently, with the advancements in neural machine translation and text-to-speech systems, researchers have strived to replicate this isochrony automatically, aiming to preserve the speech-pause

structure of the original language in the translated content (Tam et al., 2022; Lakew et al., 2022).

Another way to ensure good dubbing synchronization is lip-sync. While lip-syncing is often employed to ensure synchronicity in dubbing, it presents significant challenges. Lip-syncing may force the translated dialogue to unnaturally conform to the lip movements of the original actors, potentially compromising the accuracy and fluidity of the translation. This often results in awkward or stilted dialogue, which can spoil the overall viewing experience. Additionally, due to the linguistic differences between languages, perfect lip-syncing can be impractical, leading to less faithful representations of the original content. Consequently, although lip-syncing can enhance visual alignment, it is not the optimal approach for achieving high-quality dubbing, especially when the goal is to maintain the natural flow and meaning of the original speech (Brannon et al., 2023). Research has demonstrated that integrating isochronic translation into AI dubbing significantly enhances the quality and naturalness of dubbed content, making it more acceptable to global audiences. By preserving the timing and rhythm of the original speech, these systems not only improve the technical quality of the translation but also maintain the emotional and narrative integrity of the content (Chronopoulou et al., 2023a).

1.1 Contribution

In this work we present a new isochronic metric, ‘IsoChronoMeter’ (ICM), and evaluation dataset for isochronic translation and demonstrate that ‘normal’ translations, even by state-of-the-art systems based on LLMs and human translations, without isochrony in mind, do not achieve a good level of isochronic translation. This highlights the importance of developing specialised translation systems

that are able to perform isochronic translation.

2 Background

2.1 Isochronic translation and metrics

Initial approaches that wanted to achieve isochronic translation focused on isometric translation (Federico et al., 2020; Karakanta et al., 2020; Lakew et al., 2021b,a), where the aim of MT systems was to translate text to achieve a similar target length. Spoken language translation benchmarks included ‘isometric’ subtasks (Anastasopoulos et al., 2022). However, research showed (Brannon et al., 2023) that isometric translations do not result in temporally synchronized speech after dubbing, i.e. isometricity does not really correlate with isochronicity.

This led to the most recent approaches focusing on isochronic translation instead (Wu et al., 2022; Chronopoulou et al., 2023b). However, this direction of research is fairly new: a dedicated *dubbing* task in spoken language translation benchmarks was first introduced in 2023 (Agarwal et al., 2023), and the degree of isochronicity is either measured subjectively by humans (Federico et al., 2020) or approximated via auxiliary metrics such as phoneme-based evaluation metrics (Chronopoulou et al., 2023a). VideoDubber (Wu et al., 2022) was among the first to successfully employ automatic duration predictors to evaluate isochronicity of the translated text, but their ‘isochronic’ metric is still based on human feedback, and hence cannot be applied at scale. Therefore, we conclude that there is a need to evaluate isochronic translations automatically; furthermore, since automatic dubbing pipelines in practice work with a pipeline approach (i.e. first running ASR and then later translating), it is crucial to introduce a text-based isochronic translation evaluation suite.

2.2 Evaluation Datasets

Collecting translation datasets requires a lot of effort especially for spoken data. Existing work includes Must-C (Di Gangi et al., 2019), GigaST (Ye et al., 2023), CoVost-2 (Wang et al., 2020) and Anim-400K (Cai et al., 2024). Datasets that specifically focus on isochronic translation using professional dubbing services only seem to exist privately (Brannon et al., 2023). In our work, we choose CoVost-2 due to its permissible licenses and availability of languages.

2.3 Identified challenges.

A full isochrony estimation would require humans to read out the given original text and the translated text. Additionally, one would need to attempt to find speakers that have similar speaking rates in their respective languages. We propose to overcome this by a novel isochrony metric that is easy to compute without the need of human annotations (i.e. human speech) and a joined isochrony and translation quality metric without the need of gold annotations.

3 Method

3.1 Metrics

3.1.1 IsoChronoMeter (ours) - automatic reference-free isochrony estimation

To compute isochrony metrics, we utilize the open-source TTSMMMS project¹, which is based on Vits TTS (Kim et al., 2021) and MMS (Pratap et al., 2023), which supports multiple languages. Specifically, we use the duration predictor component to estimate the durations of the original text and translated texts generated by different machine translation (MT) models. As an isochrony metric, we apply a simple relative absolute error formula. Since the duration predictors for most languages are trained on similar domains (biblical texts) and share the same architecture, we expect them to produce similar durations adjusted to the average speaking rate of each language. Therefore, we can assume that if the texts are isochronic, their durations will be close. Concretely, IsoChronoMeter (ICM) is:

$$ICM = \left\| \frac{MMS(original) - MMS(translated)}{MMS(original)} \right\|_2^2 \quad (1)$$

Therefore, ICM is 0 if the duration of the original audio length prediction and the translated audio length prediction are the same; otherwise ICM represents a percentage of how much the two audio durations deviate from one another, e.g. ICM = 0.5 means that one of the audio duration predictions is half the duration prediction of the other.

3.1.2 Blaser2.0 - automatic reference-free machine translation quality estimation

To estimate MT quality (QE), we utilise BLASER2.0 models (Chen et al., 2023), based on

¹Only a github is available: <https://github.com/wannaphong/ttsmms>

SONAR embeddings (Duquenne et al., 2023), to predict cross-lingual semantic similarities between the translation and original texts. Concretely,

$$QE = \text{blaser2}(\text{sonar}(\text{original}), \text{sonar}(\text{translated})) \quad (2)$$

Chen et al. (2023) show that such quality-estimation metrics outperform standard metrics such as bleu.

3.1.3 Adjusted-IsoChronoMeter - automatic reference-free joined machine translation quality and isochrony estimation

We also propose another metric based on the combination of IsoChronoMeter and Blaser, Adjusted-IsoChronoMeter (A-ICM). Concretely:

$$AICM = (1 - ICM) * QE \quad (3)$$

3.2 Effectiveness of the isochronic metric

Modern TTS systems such as Elevenlabs² or Rask AI³ are able to produce realistic voices and voice-clones in multiple languages. These synthetic voices share incredible similarity with human voices. Therefore, we argue that using TTS as a proxy for the duration of human speech is effective. However, since we use a duration predictor for a TTS system, we need to show that the duration predictor is faithful to the real duration of a TTS system. To show this, we conduct a simple validation against an internal dataset of a few hours of English audio data, see Figure 1. Concretely, for each audio file we generate the ‘original’ TTS-generated audio sample and compare it against three predictions. Firstly, we compare against a ‘repeat run’, i.e. we generate a second audio file using the same TTS provider. Interestingly, the repeat run does not produce 0 or close to 0 error, in fact for < 15 words the error is above 5%. Secondly, we compare against our standard duration predictor. Finally, we also compare against a fine-tuned version of the duration predictor. We find that for small word counts the error is quite significant for all three, but especially for the not fine-tuned duration predictor. For $x > 15$, however, all three curves start converging and are within 5% error of one another. Therefore our metric becomes effective after a sufficiently large threshold of words.

²elevenlabs.com

³rask.ai

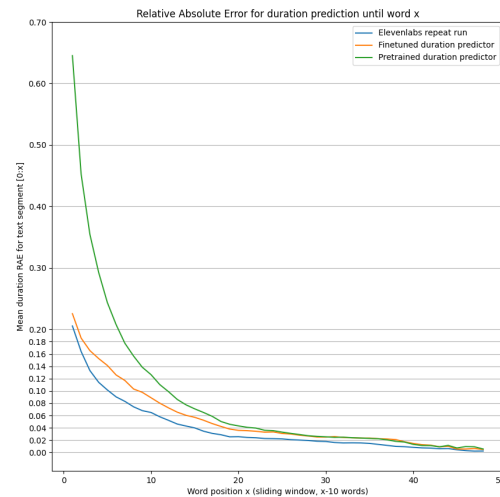


Figure 1: Dataset on English data. On the y-axis there is the relative absolute error between an original TTS-generated audio-sample and the associated prediction. On the x-axis is the number of total words used for the audio sample / prediction. Three curves show a secondary TTS-generated audio-sample (interestingly showing a big error for a few words), a fine-tuned duration predictor and the original duration predictor.

3.3 Dataset filtering

To demonstrate our metric and the need for isochronic translation engines, we create a small high-quality dataset from the CoVoST-2 (Wang et al., 2020), which is based on CommonVoice (Ardila et al., 2020). Specifically, taking into account the effectiveness of our metric after a specific threshold, we first filter the CoVoST-2 dataset by size. To find a good trade-off between dataset size and metric efficiency, we plot the histogram of counts and discover that above 20 tokens strikes a good balance, see Figure 2. In particular, we observe that if we choose the number of tokens to be 25 and higher we have too few sentences, while if we choose the number of tokens to be 15 or less our duration predictor is weak, therefore 20 and above tokens is the optimal point. Additionally, we also filter the dataset based on quality rankings by humans present in the Covost dataset. Concretely, we only take data-points where there are no downvotes and at least three upvotes. The rationale behind this is to have only high quality translation samples present.

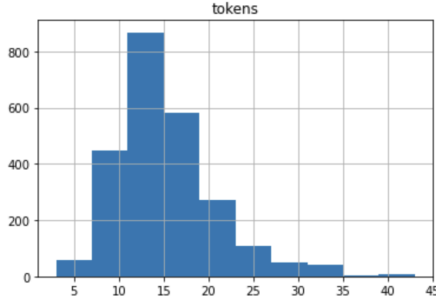


Figure 2: A histogram of sentence count vs. number of tokens in a sentence. I.e. the x-axis represents the number of tokens in a sentence, the y-axis is the total count of such sentences.

4 Results

In this section we show all the results that we produce for the WMT24 shared test suite task (Kocmi et al., 2024). Specifically, all included reference paper can be found in Appendix ???. Our evaluation, as described above, combines three metrics: IsoChronoMeter (I), Quality Estimation (Q) and Adjusted-IsoChronoMeter (A) (see Equations (1,2,3)). In particular, we received translations with a variety of systems across four language pairs: en→zh, en→es, en→ru, en→de. In total there are four tables, one per language pair.

Model	zh-I	zh-Q	zh-A
AIST-AIRC	-	-	-
Aya23	0.18	3.96	3.25
Claude-3.5	0.19	3.94	3.19
CommandR-plus	0.18	3.93	3.22
CUNI-DS	-	-	-
CUNI-NL	-	-	-
CycleL	0.22	2.49	1.94
CycleL2	0.39	2.13	1.3
Dubformer	-	-	-
Gemini-1.5-Pro	-	-	-
GPT-4	0.18	3.98	3.26
Human	0.22	3.72	2.9
HW-TSC	0.18	4.01	3.29
IKUN	0.19	3.84	3.11
IKUN-C	0.21	3.76	2.97
IOL_Research	0.19	3.98	3.22
Llama3-70B	0.19	3.99	3.23
Mistral-Large	-	-	-
MSLC	-	-	-
NVIDIA-NeMo	0.21	3.9	3.08
Occiglot	-	-	-
ONLINE-A	0.18	4.03	3.3
ONLINE-B	0.18	3.91	3.21
ONLINE-G	0.19	3.91	3.17
ONLINE-W	0.18	3.95	3.24
Phi-3-Medium	-	-	-
TranssionMT	-	-	-
TSU-HITs	-	-	-
Unbabel-Tower70B	0.18	3.95	3.24
UvA-MT	0.2	4	3.2
Yandex	-	-	-
ZMT	-	-	-

Table 1: Metrics comparison across different systems. Translation from English into: zh (Chinese). Metrics correspond to: I = IsoChronoMeter (↓), Q = Quality Estimation (↑), A = Adjusted-IsoChronoMeter (↑).

Model	es-I	es-Q	es-A
AIST-AIRC	-	-	-
Aya23	0.48	4.61	2.4
Claude-3.5	0.5	4.59	2.3
CommandR-plus	0.5	4.59	2.3
CUNI-DS	-	-	-
CUNI-NL	-	-	-
CycleL	0.5	3.52	1.76
CycleL2	-	-	-
Dubformer	0.47	4.6	2.44
Gemini-1.5-Pro	-	-	-
GPT-4	0.5	4.6	2.3
Human	0.48	4.42	2.3
HW-TSC	-	-	-
IKUN	0.46	4.56	2.46
IKUN-C	0.45	4.5	2.48
IOL_Research	0.48	4.6	2.39
Llama3-70B	0.49	4.61	2.35
Mistral-Large	-	-	-
MSLC	0.47	4.61	2.44
NVIDIA-NeMo	0.47	4.62	2.45
Occiglot	0.51	4.43	2.17
ONLINE-A	0.48	4.6	2.39
ONLINE-B	0.49	4.64	2.37
ONLINE-G	0.48	4.6	2.39
ONLINE-W	0.47	4.59	2.43
Phi-3-Medium	-	-	-
TranssionMT	0.5	4.62	2.31
TSU-HITs	0.25	3.39	2.54
Unbabel-Tower70B	0.5	4.62	2.31
UvA-MT	-	-	-
Yandex	-	-	-
ZMT	0.49	4.61	2.35

Table 2: Metrics comparison across different systems. Translation from English into: es (Spanish). Metrics correspond to: I = IsoChronoMeter (↓), Q = Quality Estimation (↑), A = Adjusted-IsoChronoMeter (↑).

Model	ru-I	ru-Q	ru-A
AIST-AIRC	-	-	-
Aya23	0.48	4.91	2.55
Claude-3.5	0.49	4.95	2.52
CommandR-plus	0.49	4.9	2.5
CUNI-DS	0.47	4.86	2.58
CUNI-NL	-	-	-
CycleL	0.39	3.15	1.92
CycleL2	0.3	2.52	1.76
Dubformer	0.42	4.82	2.8
Gemini-1.5-Pro	-	-	-
GPT-4	0.47	4.93	2.61
Human	0.53	4.82	2.27
HW-TSC	-	-	-
IKUN	0.42	4.84	2.81
IKUN-C	0.41	4.77	2.81
IOL_Research	0.47	4.93	2.61
Llama3-70B	0.49	4.94	2.52
Mistral-Large	-	-	-
MSLC	-	-	-
NVIDIA-NeMo	0.48	4.93	2.56
Occiglot	-	-	-
ONLINE-A	0.48	4.91	2.55
ONLINE-B	0.47	4.93	2.61
ONLINE-G	0.51	4.93	2.42
ONLINE-W	0.47	4.92	2.61
Phi-3-Medium	-	-	-
TranssionMT	0.47	4.93	2.61
TSU-HITs	0.34	3.66	2.42
Unbabel-Tower70B	0.49	4.92	2.51
UvA-MT	-	-	-
Yandex	0.48	4.83	2.51
ZMT	0.48	4.91	2.55

Table 3: Metrics comparison across different systems. Translation from English into: ru (Russian). Metrics correspond to: I = IsoChronoMeter (↓), Q = Quality Estimation (↑), A = Adjusted-IsoChronoMeter (↑).

5 Findings

We identify three main findings. Firstly, isochrony is not the natural way of translation (even for humans). Secondly, systems designed for dubbing, such as DubFormer, or multi-linguality, such as Aya23, outperform their ‘standard’ counter-parts. Finally, the metric itself is powerful and determines systems that are better at dubbing without gold annotations.

5.1 Isochrony does not come automatically

We discover that across all language pairs, the smallest isochronic score (ICM) that we discover

is 0.18, which means that the translated audio duration prediction is almost 18% longer or shorter than the original audio prediction.

Model	de-I	de-Q	de-A
AIST-AIRC	0.35	4.69	3.05
Aya23	0.38	4.68	2.9
Claude-3.5	0.39	4.7	2.87
CommandR-plus	0.38	4.68	2.9
CUNI-DS	-	-	-
CUNI-NL	0.33	4.62	3.1
CycleL	0.4	3.65	2.19
CycleL2	0.4	3.65	2.19
Dubformer	0.32	4.51	3.07
Gemini-1.5-Pro	-	-	-
GPT-4	0.39	4.72	2.88
Human	0.38	4.47	2.77
HW-TSC	-	-	-
IKUN	0.34	4.57	3.02
IKUN-C	0.34	4.5	2.97
IOL_Research	0.37	4.7	2.96
Llama3-70B	0.39	4.73	2.89
Mistral-Large	-	-	-
MSLC	0.36	4.61	2.95
NVIDIA-NeMo	0.37	4.72	2.97
Occiglot	0.46	4.55	2.46
ONLINE-A	0.37	4.68	2.95
ONLINE-B	0.37	4.6	2.9
ONLINE-G	0.36	4.69	3
ONLINE-W	0.37	4.66	2.94
Phi-3-Medium	-	-	-
TranssionMT	0.37	4.6	2.9
TSU-HITs	0.34	3.37	2.22
Unbabel-Tower70B	0.38	4.68	2.9
UvA-MT	-	-	-
Yandex	-	-	-
ZMT	0.37	4.68	2.95

Table 4: Metrics comparison across different systems. Translation from English into: de (German). Metrics correspond to: I = IsoChronoMeter (↓), Q = Quality Estimation (↑), A = Adjusted-IsoChronoMeter (↑).

5.2 Most promising systems

The most promising systems that are overall better at isochronic translation as well as translation quality are DubFormer, Ikun, Ikun-C (Liao et al., 2024) and Cuni-NL (Hrabal et al., 2024). For some language pairs, some big players such as GPT-4, Nemo and ‘Online A’ perform well as well as some specialised systems HW-TSC (Wu et al., 2024) and MSLC (Larkin et al., 2024). Aya23 outperforms its

backbone model CommandR-plus, which is intuitive and show that multi-linguality helps MT and isochronic-MT.

5.3 Nuances in the metric

Overall we discover that the joined metric is very powerful in ranking systems. We discover an edge case for en→zh, where TSU-HITs has a poor translation quality and likely drops parts of the translation, resulting in poor quality estimate scores, but it has excellent isochrony scores and adjusted isochrony scores. Therefore, we recommend using a performance threshold when applying the metric.

6 Conclusion & Future Work

We motivate the importance of isochronic translation. To this end, we presented a novel and simple metric to evaluate isochrony that does not require gold annotations. We evaluated the shared task and discovered that: 1. Isochrony does not come naturally for translation systems, including human (non-isochronic) translation; 2. Systems and LLMs that are designed for multi-linguality or dubbing perform better on our main metric ‘Adjusted-IsoChronoMeter’, which combines isochrony and machine translation quality; 3. The metric requires some nuance, as systems that drop parts of the translation might have a good isochrony score, but bad translation quality score - overall biasing them towards a better A-ICM.

6.1 Future directions

There are several future directions that we identify. Firstly, isochronic translation itself is a promising direction and automatic metrics such as IsoChronoMeter can help with advancing this field. Secondly, extending the benchmark to include gold human translation designed for dubbing. Finally, a more detailed evaluation and improvement of the metric itself; specifically, we believe better duration predictors are possible, and more rigorous evaluation, including using gold annotations and on more language pairs.

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